



## Main Features

- ♦ Edge AI in-vehicle/rail computer
- ♦ Built-in NVIDIA® Jetson Orin™ Nano SOM, up to 40(sparse) INT8 TOPS compute
- ♦ 3-CH MIPI SerDes, 1080p60/4Kp30 over 15m cable for MIPI CAM
- ♦ HEVC/H.265 hardware CODEC, 11x 1080p30 compute power (decoded)
- ♦ Wide range operating temperature of -30~70°C

- ♦ The rugged, fanless design with IP67 rating
- ♦ Ultra-speed PCIe 4.0 x4 NVMe SSD for data integrity
- ♦ NEXCOM Acceleration Linux (NAL) OS w/ JetPack 5.1.1 integrated
- ♦ Expandable for LTE/5G NR & Wi-Fi 5/6
- ♦ 9~36V DC-in with ignition control & OCP/OVP
- ♦ CE/FCC, UKCA certified

## Product Overview

AI has become an essential component of automated vehicle technologies. With built-in cost-effective performance/watt-cost NVIDIA® Jetson Orin™ Nano SOM, ATC 3520 can deliver up to 40(sparse)INT8 TOPS for running modern AI workloads while consuming 15W low power. This is suitable for AI power IoT gateway, OHV AI Edge recognition, AI traffic sign control, and factory automation/machine vision, to enhance the productivity and lowering TCO.

ATC 3520 is a fanless, compact, and IP67 certified computer. As an AI in-vehicle computer for inference computing, it features 9~36VDC with IGN control, up to 3-CH MIPI SerDes interface to access MIPI CAM with 4Kp30/1080p60 resolution, CANBus for mmWave radar and others I/O peripheral, like 2 GbE, 2 USB 3.2, isolation CANBus, 2 RS232, Console, DI/DO, OTG, and HDMI, to meet any sophisticated applications.

With the 5G NR, Wi-Fi 5/6 modules installed, ATC 3520 can enhance AI inference through Cloud Service Provider (CSP). As for harsh environment applications, ATC 3520 can operate at a wide range temperature of -30~70°C and meet the MIL-STD-810G military standard for vibration and shock resistance. In terms of regulation, ATC 3520 is compliant with CE/FCC Class A, UKCA and Emark (E13)/EN50155.

## Specifications

### NVIDIA® Jetson Orin™ Nano SOM

- ♦ 6-core (Orin™ Nano 8GB/4GB) Arm® Cortex A78AE 64-bit CPU
- ♦ 512/1024-core + 16/32-core Tensor, 625MHz, Ampere
- ♦ 40 INT8 TOPS (Orin™ Nano 8GB), 20 INT8 TOPS (Orin™ Nano 4GB), sparse
- ♦ OpenGL 4.6, OpenGL ES 3.2, and Vulkan 1.1, CUDA10
- ♦ 260-pin SO-DIMM form factor compatible with Orin NX
- ♦ NVIDIA® JetPack 5.1.1

### Memory

- ♦ 4GB/8GB 64-bit/128-bit LPDDR5 for Nano 4GB/8GB 2133MHz

### Storage/Boot Disk

- ♦ 1 x M.2 2280/3080 Key M PCIe 3.0 x4 NVMe SSD, 128GB in default

### Expansion

- ♦ 1 x Full size mPCIe socket (PCIe 4.0 + USB 2.0)
- ♦ 1 x M.2 3042/3052 Key B socket (USB 3.2) with 2 x micro SIM slots

### Display

- ♦ 1 x HDMI 2.0A/B, up to 3840 x 2160@60Hz

### G-Sensor

- ♦ 3D accelerometer and 3D gyroscope, ST LSM6DSLTR

### GbE

- ♦ 2-port GbE, X-coded
- ♦ 9K byte Jumbo frame, PTP (IEEE 1588) support
- ♦ Controller: Intel® I210-IT

### MIPI CSI-2 SerDes

- ♦ Up to 3 x individual channel (1080p60/720p30 resolution)
- ♦ Thine SerDes solution (V-by-One® HS)
- ♦ Integrated with 3rd party MIPI SerDes camera (IP67 rating)
  - 1080p60 CAM: CAM1-MT1080-IP7-15m (P/N: 10AT0108001X0)
  - 720p30 CAM: CAM1-MT720-IP7-15m (P/N: 10AT0072001X0)

### USB

- ♦ 2 x USB 3.2, type A
  - 5V@900mA each
  - up to 5Gbit/s link speed & compliance with USB 2.0 (LS/FS/HS link speed)
- ♦ 1 x OTG micro USB

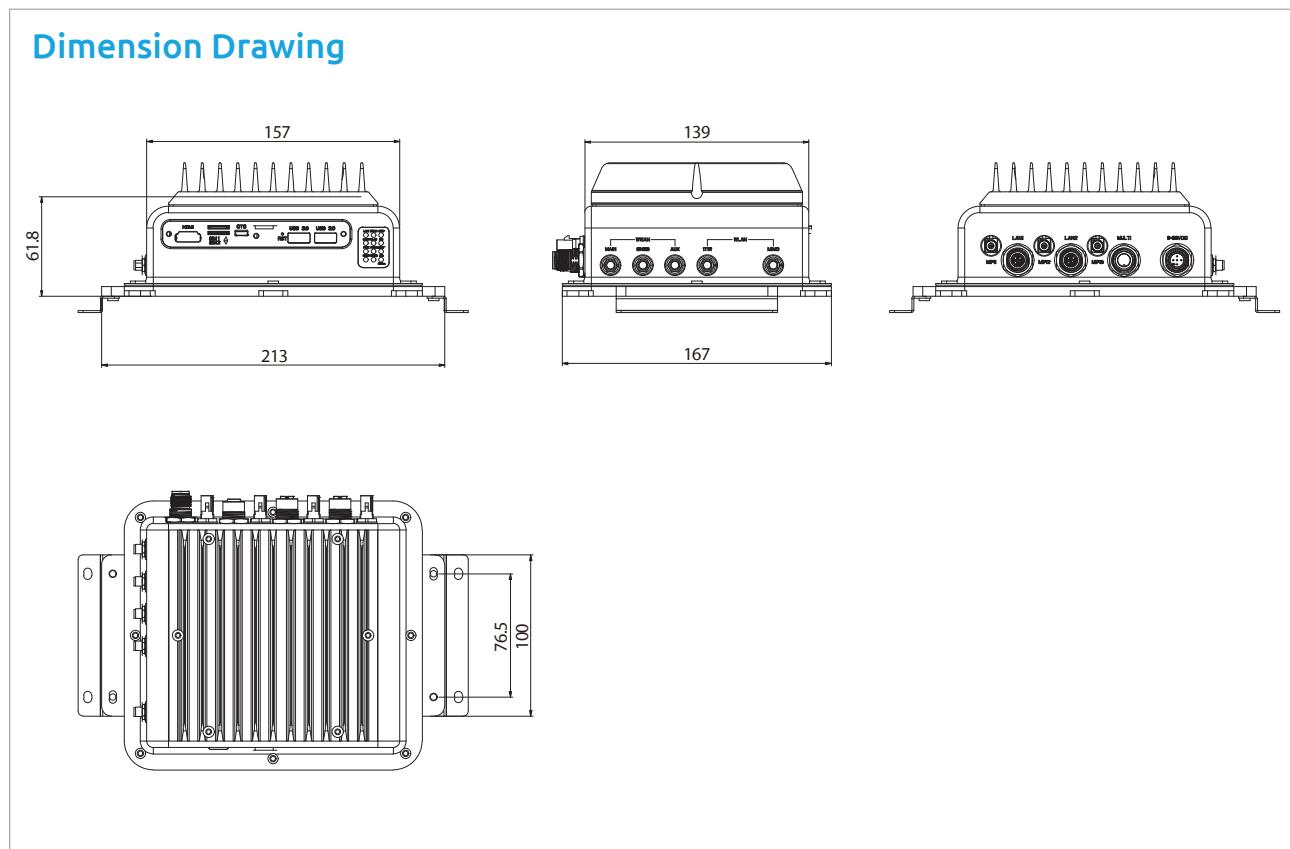
### Serial Port

- ♦ 1 x RS232 (Tx, Rx, CTS, RTS)
- ♦ 1 x RS232 (Tx, Rx)
- ♦ 1 x Console port (Tx, Rx)
- ♦ RS232 working voltage, ±9V, baud rate up to 115.2kb/s

### DI/DO (reserved)

- ♦ 4-Bit input
  - Source: 9~36VDC (12V@0.6mA/24V@1.2mA)
  - External: 0~33VDC pull-high, high-level, 3.3 - 33VDC; low-level, 0-2 VDC
- ♦ 4-Bit output
  - Source: 9~36VDC (nominal 35mA@24V)
  - External: 5~27VDC pull-high, sink current w/ 220mA for each bit, 500mA max (@25C)
- ♦ Source or external can be selected by software (default: source type)

## Dimension Drawing



### CANBus

- ♦ 1 x CAN 2.0A/2.0B
- ♦ IEC 61000-4-2 Electrostatic Discharge (ESD):  $\pm 4\text{KV}/8\text{KV}$  (contact/air, whole system)
- ♦ 2.5KV isolated

### GPS

- ♦ U-blox NEO-M9N GNSS module for GPS/Gloness/QZSS/Galileo/Beidou
- ♦ Optional DR (dead reckoning) function, NEO-M9V

### Power Supply

- ♦ Nominal voltage: 9~36V
- ♦ Cranking voltage: 6V~9V (less than 20 sec)
- ♦ OCP & UVP (shut down once exceeding 37V)
- ♦ Ignition on/off control & programmable on/off delay timer
- ♦ Optional for remote power on/off control

### I/O Ports, Front-Plate

- ♦ 12 x LED indicators
- ♦ Reset button, 1 x OTG
- ♦ 2 x Micro SIM slots, 1 x HDMI, 2 x USB 3.2

### I/O Ports, Rear-Plate

- ♦ 9~36VDC-in, S-coded
- ♦ 3 x Fakra z-code & 2 x GbE, X-coded
- ♦ M12 multi-port (2 x RS232 & 1 x console, 1 x CAN)

### I/O Ports, Side-Plate

- ♦ 2 x Antenna holes for Wi-Fi 5/6 modules (PR-SMA ant.)
- ♦ 2 x Antenna holes for LTE/5G module (SMA ant.)
- ♦ 1 x Antenna hole for GNSS (RP-SMA ant.)

### Dimensions & Weight

- ♦ 213mm x 167mm x 82.8mm (w/ mount bracket)
- ♦ 2.4kg

### Environment

- ♦ Operating temperatures: -30°C~70°C NVIDIA® Jetson Orin™ Nano@7W/10W15W

- ♦ Storage temperatures: -40°C~85°C
- ♦ Relative humidity: 10%~95% (non-condensing)

### Vibration & Shock

- ♦ Vibration in operating
  - MIL-STD-810G, 514.6C, Procedure 3, Category 4
  - IEC 60068-2-64: 2.0g@5~500 Hz
  - MIL-STD-810G, 514.6E, Procedure 1, Category 24, 7.7g approx.
- ♦ Shock
  - Operating: MIL-STD-810G, Method 516.6, Procedure I, functional shock=20g
  - Non-operating: MIL-STD-810G, Method 516.6, Procedure V, crash hazard shock test=75g

### Certifications

- ♦ CE approval, FCC Class A, UKCA

### Operating System

- ♦ NEXCOM Acceleration Linux (NAL)
  - NV Jetpack 5.1.1 package
  - NEXCOM custom functions (GNSS, 5GNR, 6-axis sensor, MCU control)
  - V4L2
  - Ubuntu 20.04@Kernel 5.10

### External Cable

- ♦ Power extension cable, 20cm
- ♦ M12 multi-port adapter cable, 20cm

## Ordering Information

### ♦ 3520-IP7-3M (P/N: 10AT0352004X0)

IP67 rating edge AI compute, NVIDIA® Jetson Orin™ Nano SOM, 4GB LPDDR5, 128GB NVMe, 3 x MIPI VBO, 2 x GbE, 2 x RS232, 2 x USB 3.0